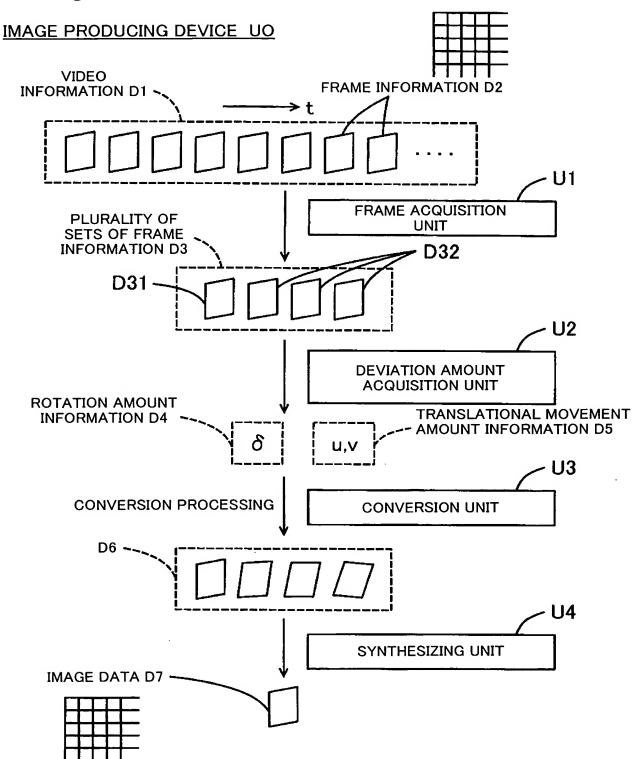


Fig.3



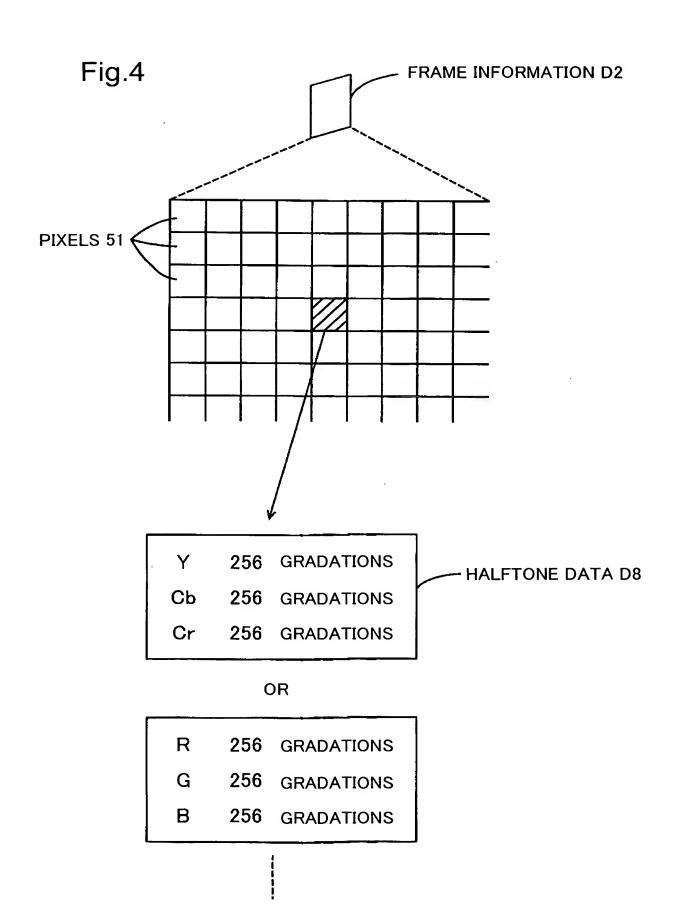
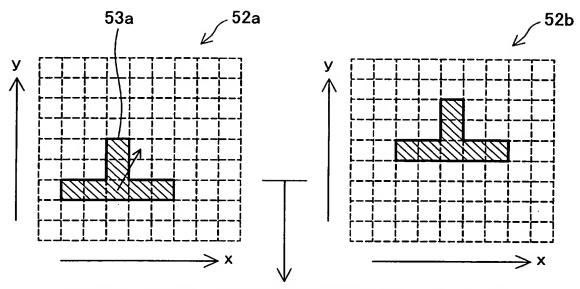
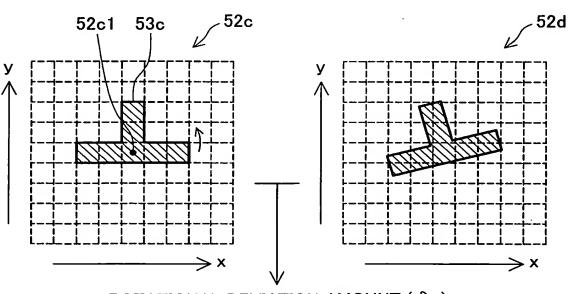


Fig.5



TRANSLATIONAL DEVIATION AMOUNT (ua, va) = (1, 2)



ROTATIONAL DEVIATION AMOUNT (δ a)

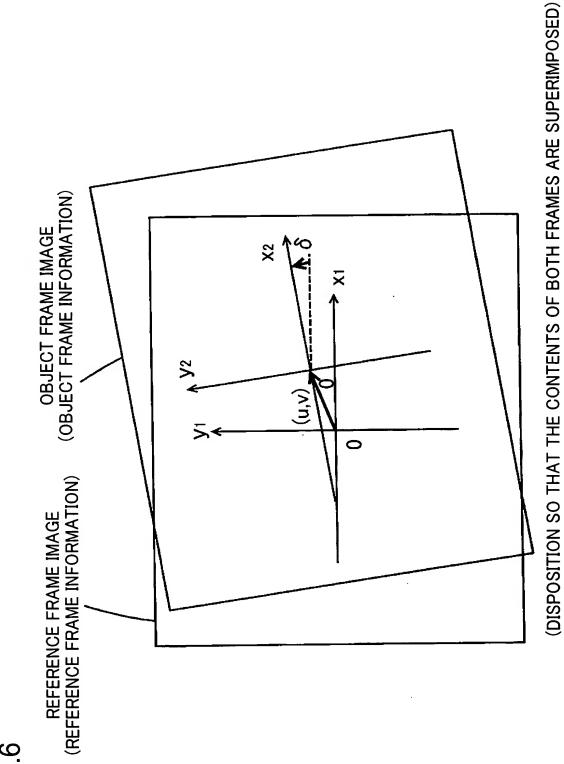


Fig.6

Fig.7

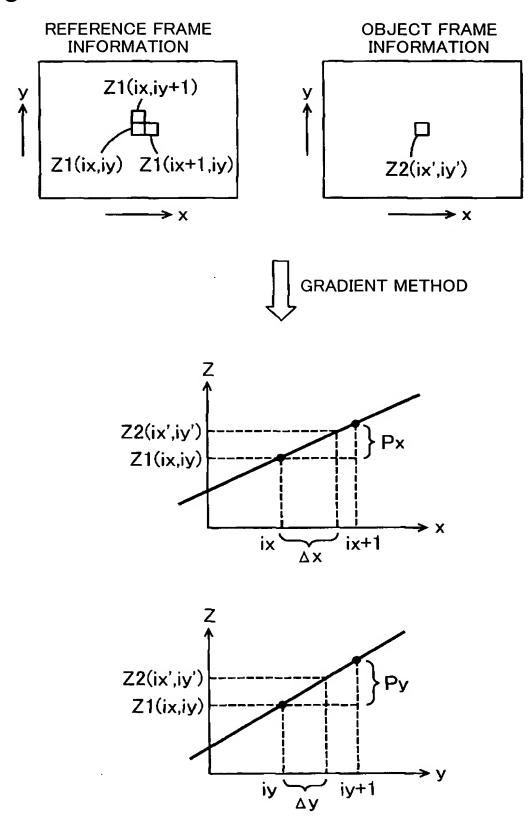


Fig.8

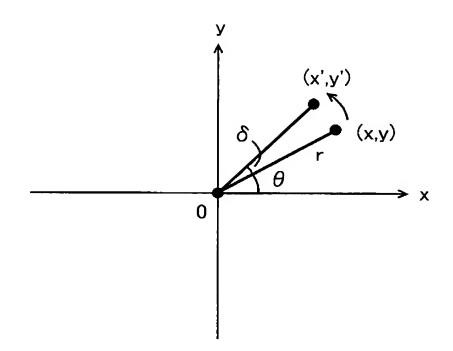
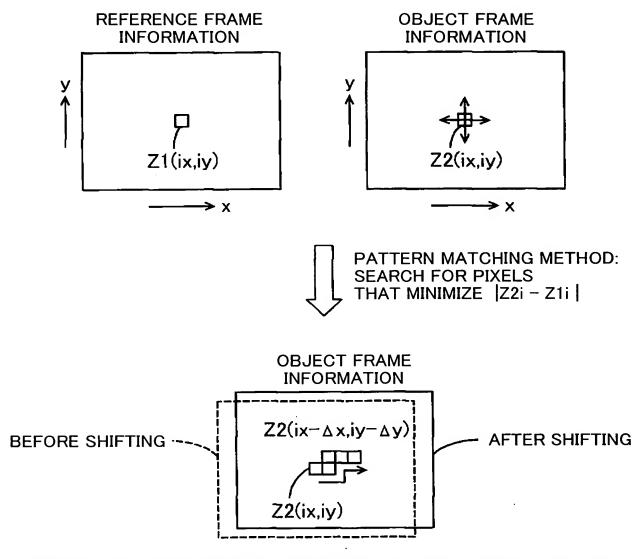


Fig.9



AMOUNT OF TRANSLATIONAL MOVEMENT IN PIXEL UNITS = $(\Delta x, \Delta y)$

Fig.10

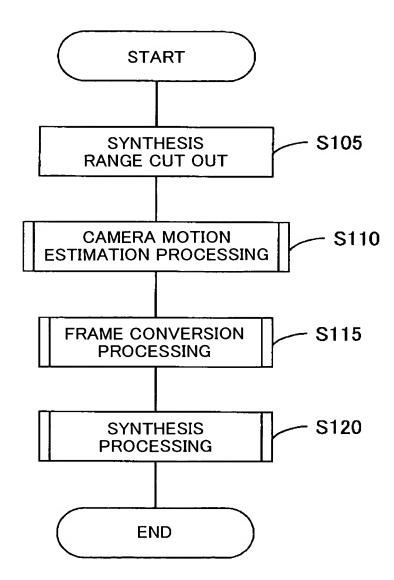


Fig.11

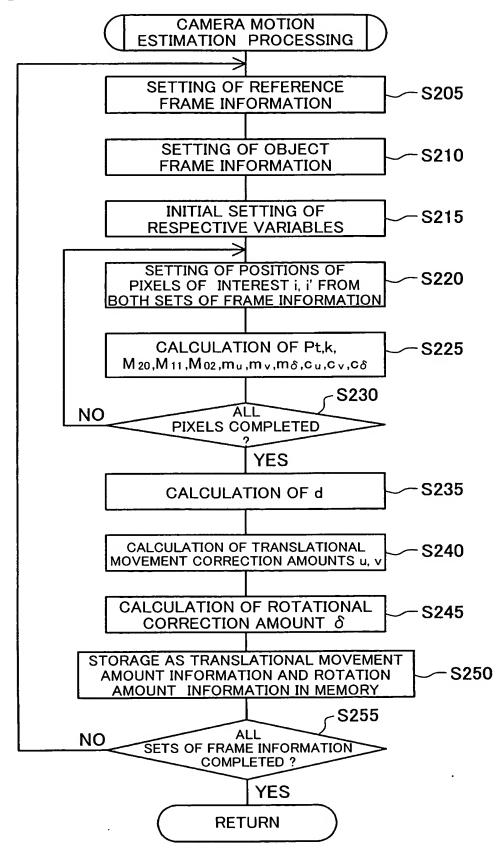


Fig.12

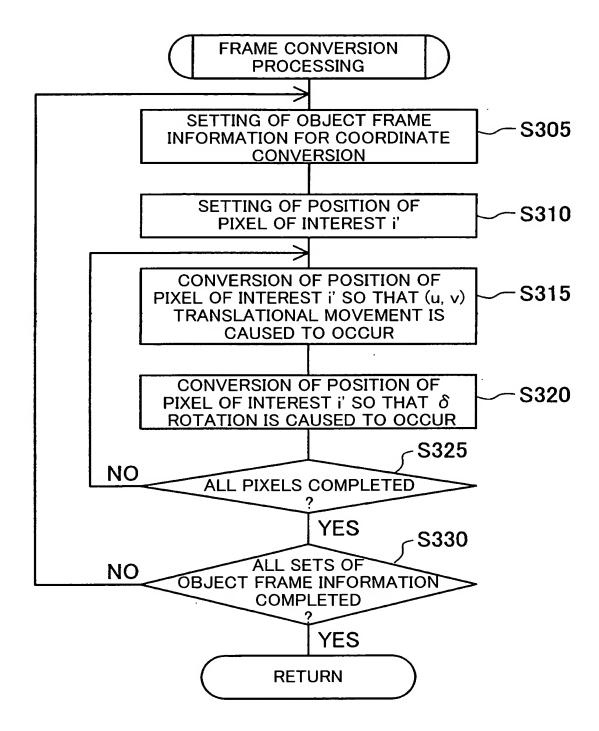


Fig.13

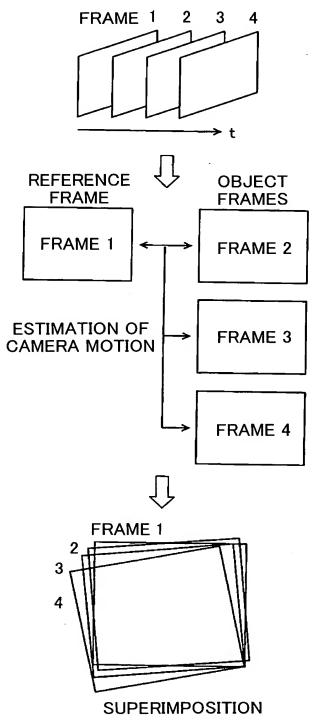


Fig.14

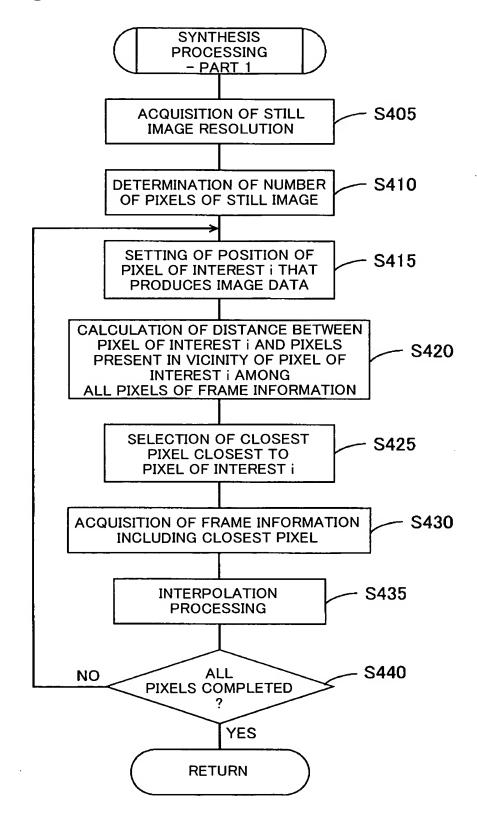
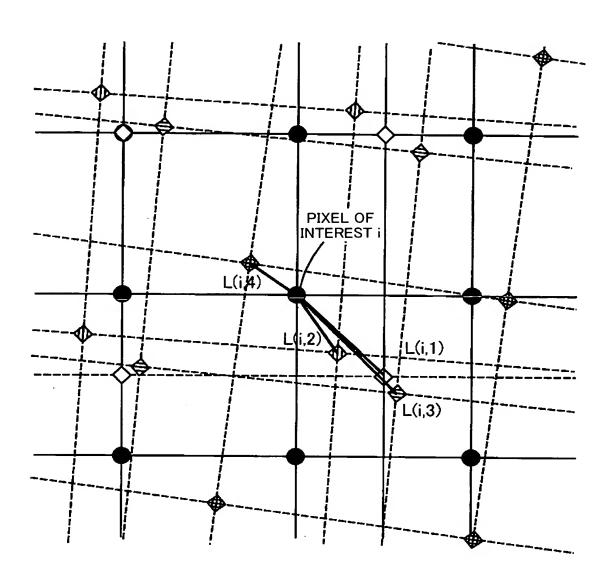


Fig.15



- PIXELS OF PRODUCED IMAGE

- ♦ PIXELS OF FRAME 3 ♦ PIXELS OF FRAME 4

Fig.16

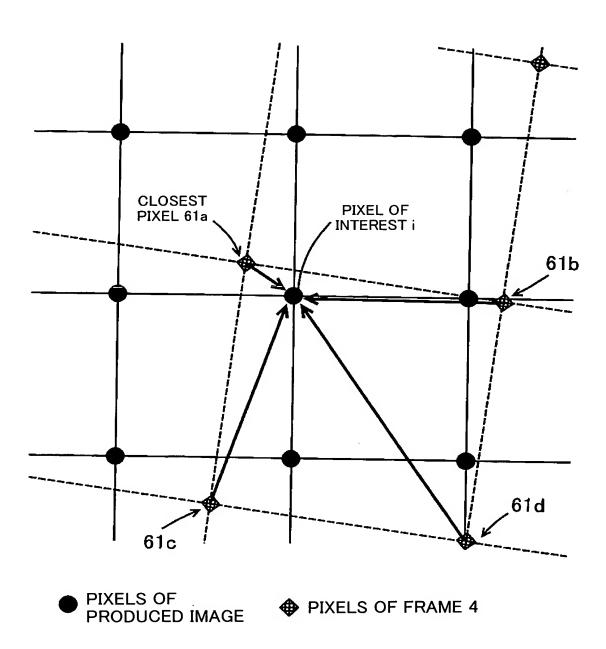


Fig.17

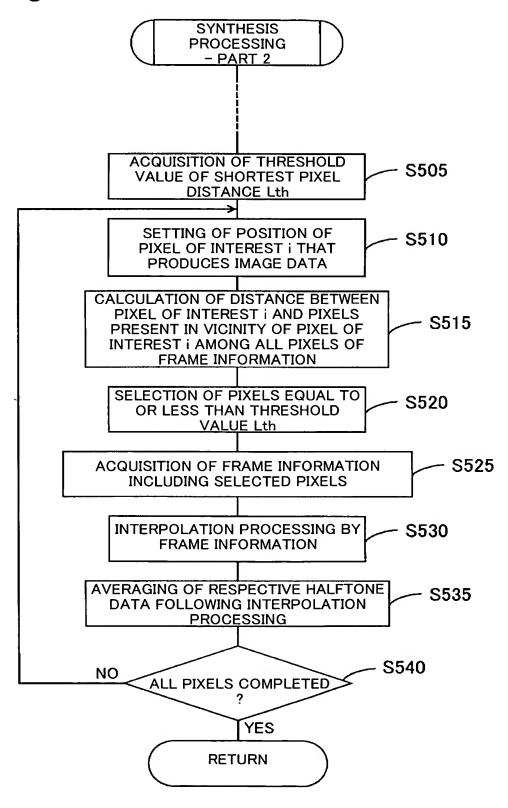
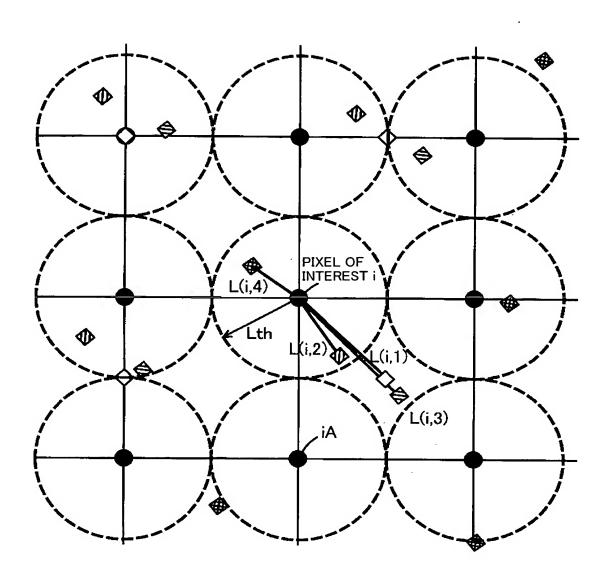


Fig.18



- PIXELS OF PRODUCED IMAGE
- ♦ PIXELS OF FRAME 3 ♦ PIXELS OF FRAME 4

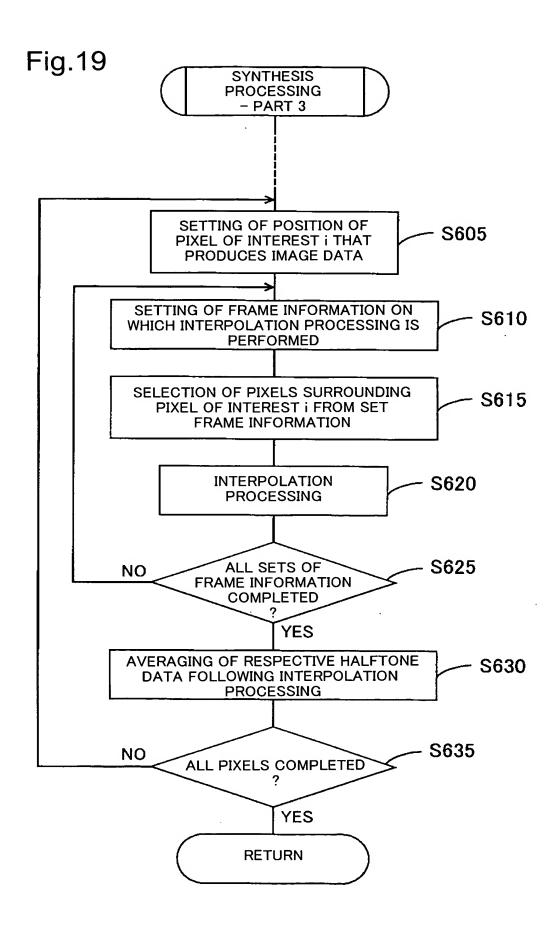


Fig.20



